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UNIVERSITI SAINS MALAYSIA

Second Semester Examination  
2007/2008 Academic Session  
*Peperiksaan Semester Kedua  
Sidang Akademik 2007/2008*

April 2008  
*April 2008*

**ESA 362/3 – Aircraft Flight Control**  
*Kawalan Penerbangan Pesawat*

Duration : 3 hours  
*[Masa : 3 jam]*

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**INSTRUCTION TO CANDIDATES**

**ARAHAN KEPADA CALON**

Please ensure that this paper contains **NINETEEN (19)** printed pages including attachment and **FIVE (5)** questions before you begin examination.

*Sila pastikan bahawa kertas soalan ini mengandungi **SEMBILAN BELAS (19)** mukasurat bercetak termasuk lampiran dan **LIMA (5)** soalan sebelum anda memulakan peperiksaan.*

Answer **FOUR (4)** questions only.

Question number **1, 2 and 3** must be answered.

Please choose one question number **4 or 5**.

*Jawab **EMPAT (4)** soalan sahaja.*

*Soalan nombor **1, 2 dan 3** mesti dijawab.*

*Sila pilih salah satu soalan nombor **4 atau 5**.*

Student may answer the questions either in English or Bahasa Malaysia.

*Pelajar boleh menjawab soalan dalam Bahasa Inggeris atau Bahasa Malaysia.*

Each questions must begin from a new page.

*Setiap soalan mestilah dimulakan pada mukasurat yang baru.*

Appendix : Page 9 to 19

*Lampiran : Mukasurat 9 hingga 19*

1. (a) List 3 kinds of automatic flight control system?

*Senaraikan 3 jenis sistem kawalan automatik?*

**(10 marks/markah)**

- (b) Mention the autopilot modes for aircraft and their functions.

*Sebutkan jenis-jenis mod pandu automatik bagi pesawat udara dan fungsi-fungsinya.*

**(10 marks/markah)**

- (c) Please list down six steps in designing the controller (control law) for an automatic flight control system.

*Sila senaraikan enam langkah dalam merekabentuk pengawal (hukum kawalan) untuk sistem kawalan automatik penerbangan.*

**(10 marks/markah)**

- (d) Please give four equations which form the nonlinear equations of motion of the aircraft and their functions.

*Sila berikan empat jenis persamaan yang membentuk persamaan tidak linear gerak pesawat dan fungsi-fungsinya.*

**(10 marks/markah)**

- (e) Why do we need to determine a steady-state, trimmed flight condition before starting the linearization process and flight simulation.

*Mengapakah kita perlu menentukan keadaan mantap penerbangan trim sebelum memulakan proses lurus dan simulasi penerbangan.*

**(10 marks/markah)**

- (f) Please write the linear model for Longitudinal motion in the form of state space representation.

*Sila tuliskan model lurus gerak pesawat longitudinal dalam bentuk perwakilan keadaan ruang.*

**(10 marks/markah)**

- (g) What are the differences between "short period mode", and "phugoid"?

*Apakah perbezaan di antara "short period" dan "phugoid"?*

**(10 marks/markah)**

- (h) Write the approximated transfer function describing

*Tuliskan fungsi pindah yang menggambarkan*

- (i) elevator the response of angle of attack due to the elevator deflection  
*sambutan sudut serang disebabkan oleh pesongan sudut*
- (ii) "throttle" the response of airspeed due to the lever throttle  
*sambutan halaju udara di sebabkan oleh kedudukan*

**(10 marks/markah)**

- (i) Please draw the signal flow diagram (SFD) of simplified Short periodmode.

*Sila lukiskan gambarajah aliran isyarat (SFD) bagi tempoh mod "short period" yang dipemudahkan.*

**(10 marks/markah)**

- (j) Please draw the signal flow diagram (SFD) of simplified phygoid mode.

*Sila lukiskan gambarajah aliran isyarat (SFD) bagi mod-'phygoid' yang dipemudahkan.*

**(10 marks/markah)**

2. A passenger aircraft of Type A 300 is performing level flight in the undisturbed atmosphere (still air, no wind). The stationary, symmetrical flight condition is given below

*Pesawat penumpang jenis A 300 sedang membuat penerbangan di dalam keadaan atmosfera tidak terganggu ( udara tenang dan tiada angin). Keadaan penerbangan yang pegun dan secara simetri diberi seperti berikut:*

Mass of the aircraft	$m = 100,000.00 \text{ kg}$
Airspeed	$V = 120 \text{ m/s}$
Position of the centre of gravity	$(X_s - 0.25) = 0.05$
Vertical position of engine thrust	$Z_E = 2.65 \text{ m}$
The Inclination angle of engine	$\sigma = 2.2 \text{ degree}$

<i>Jisim pesawat</i>	$m = 100,000.00 \text{ kg}$
<i>Kelajuan pesawat</i>	$V = 120 \text{ m/s}$
<i>Kedudukan pusat graviti</i>	$(X_s - 0.25) = 0.05$
<i>Kedudukan menegak tujahan enjin</i>	$Z_E = 2.65 \text{ m}$
<i>Sudut condong enjin</i>	$\sigma = 2.2 \text{ degree}$

After setting up equation of motion for longitudinal flight and determining the steady-state trimmed flight condition, the data of that trim flight condition is provided as follows:

*Selepas mendapatkan persamaan gerakan bagi penerbangan secara membujur dan penentuan keadaan mantap penerbangan trim, data penerbangan dalam keadaan ini diberi seperti yang berikut:*

$$\alpha_0 = 0.0925 = 5.3^\circ$$

$$C_{L,0} = 0.74$$

$$C_{D,0} = 0.045$$

$$C_{m,0} = -0.0182$$

$$C_{\mu,0} = 0.0455 (\text{thrust coefficient})$$

$$i_{H,0} = -0.0068 = 0.39^\circ$$

- (a) Calculate the following dimensional aerodynamic derivatives:

$$M_q, M_\alpha, M_u, Z_\alpha, Z_u, X_\alpha, X_u$$

*Kira terbitan dimensi aerodinamik yang berikut:*

$$M_q, M_\alpha, M_u, Z_\alpha, Z_u, X_\alpha, X_u$$

**(50 marks/markah)**

- (b) Determine the following dimensional control derivatives:

$$M_\eta, M_f, Z_\eta, Z_f, X_\eta, X_f$$

*Tentukan terbitan dimensi kawalan yang berikut:*

$$M_\eta, M_f, Z_\eta, Z_f, X_\eta, X_f$$

**(50 marks/markah)**

3. Represent the linear equation of motion for longitudinal flight

*Sila nyatakan persamaan lurus gerak penerbangan membujur*

(a) in form of the state – space representation  $\dot{\underline{X}} = \underline{A}\underline{X} + \underline{B}\underline{U}$

*dalam bentuk perwakilan keadaan ruang  $\dot{\underline{X}} = \underline{A}\underline{X} + \underline{B}\underline{U}$*

(b) signal diagram block

*gambarajah blok isyarat*

**(100 marks/markah)**

4. Based on the approximate equation for short-period mode, determine the following:

*Berdasarkan persamaan hampir bagi mod kalaan pendek, tentukan yang berikut:*

(a) the transfer function  $f_{\alpha\eta}$

*fungsi pindah  $f_{\alpha\eta}$*

(b) the damping  $\zeta$  and natural frequency  $\omega_0$  of short period

*redaman  $\zeta$  dan frekuensi tabii  $\omega_0$  kalaan pendek*

(c) initial – and stationary characteristics of  $\alpha$  due to step input of  $\eta$

*ciri-ciri awalan dan akhiran kepegunan  $\alpha$  yang disebabkan oleh input langkah  $\eta$*

**(100 marks/markah)**

5. Based on the approximate equation for phugoid mode, determine the following:

*Berdasarkan persamaan terdekat untuk mod phugoid, tentukan yang berikut:*

(a) the transfer function  $f_{uf}$

*fungsi pindah  $f_{uf}$*

(b) the damping  $\zeta$  and natural frequency  $\omega_0$  of phugoid mode

*redaman  $\zeta$  dan frekuensi tabii  $\omega_0$  mod phugoid*

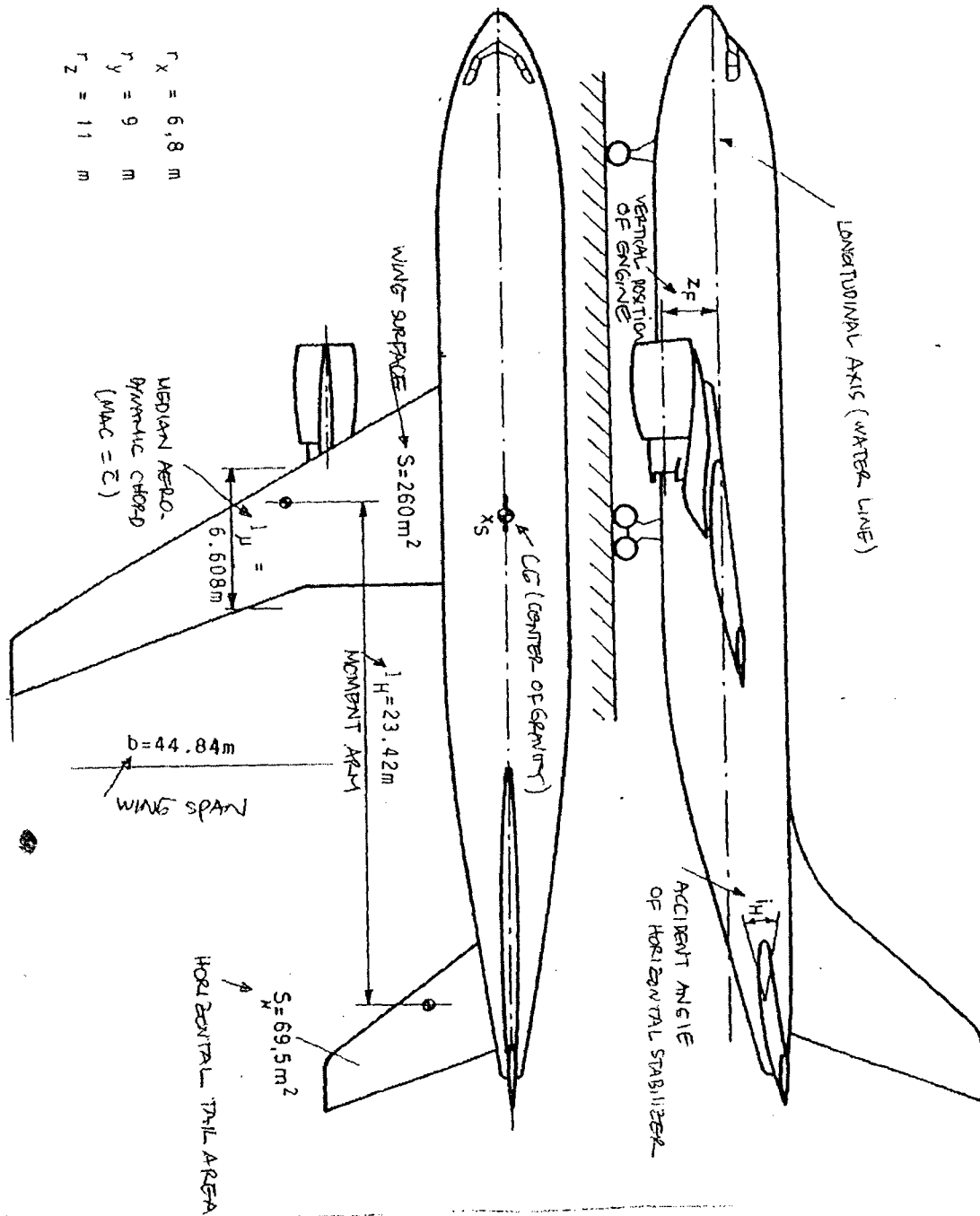
(c) initial – and stationary characteristics of  $u$  due to step input of throttle setting  $f$

*ciri-ciri awalan dan akhiran kepegunan  $u$  yang disebabkan oleh input langkah pengesetan pengawal imbang  $f$*

**(100 marks/markah)**

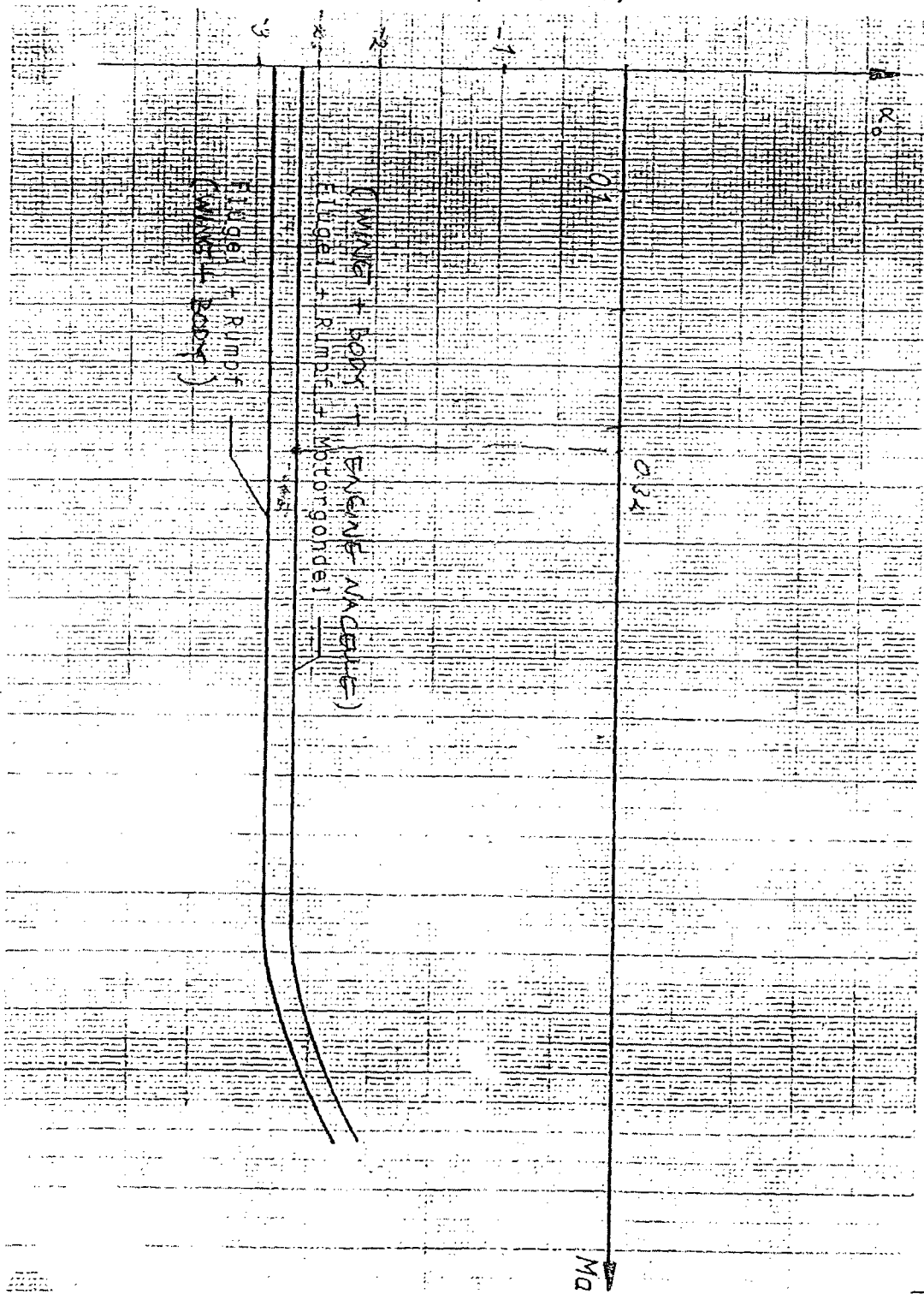


**LAMPIRAN/ATTACHMENT**



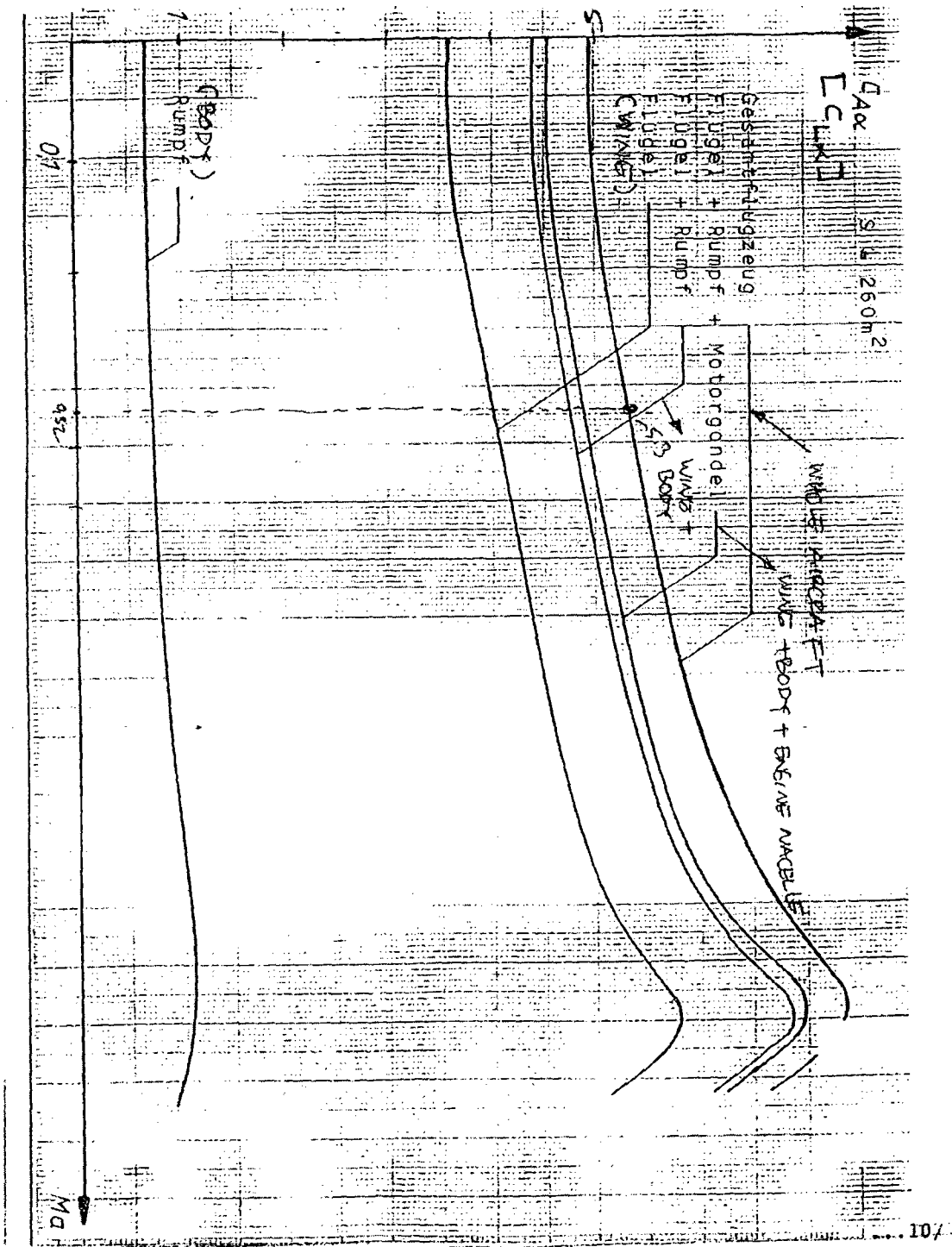
$r_x = 6,8 \text{ m}$   
 $r_y = 9 \text{ m}$   
 $r_z = 11 \text{ m}$

Anstellwinkel bei Auftrieb Null  
(ZERO LIFT ANGLE OF ATTACK)

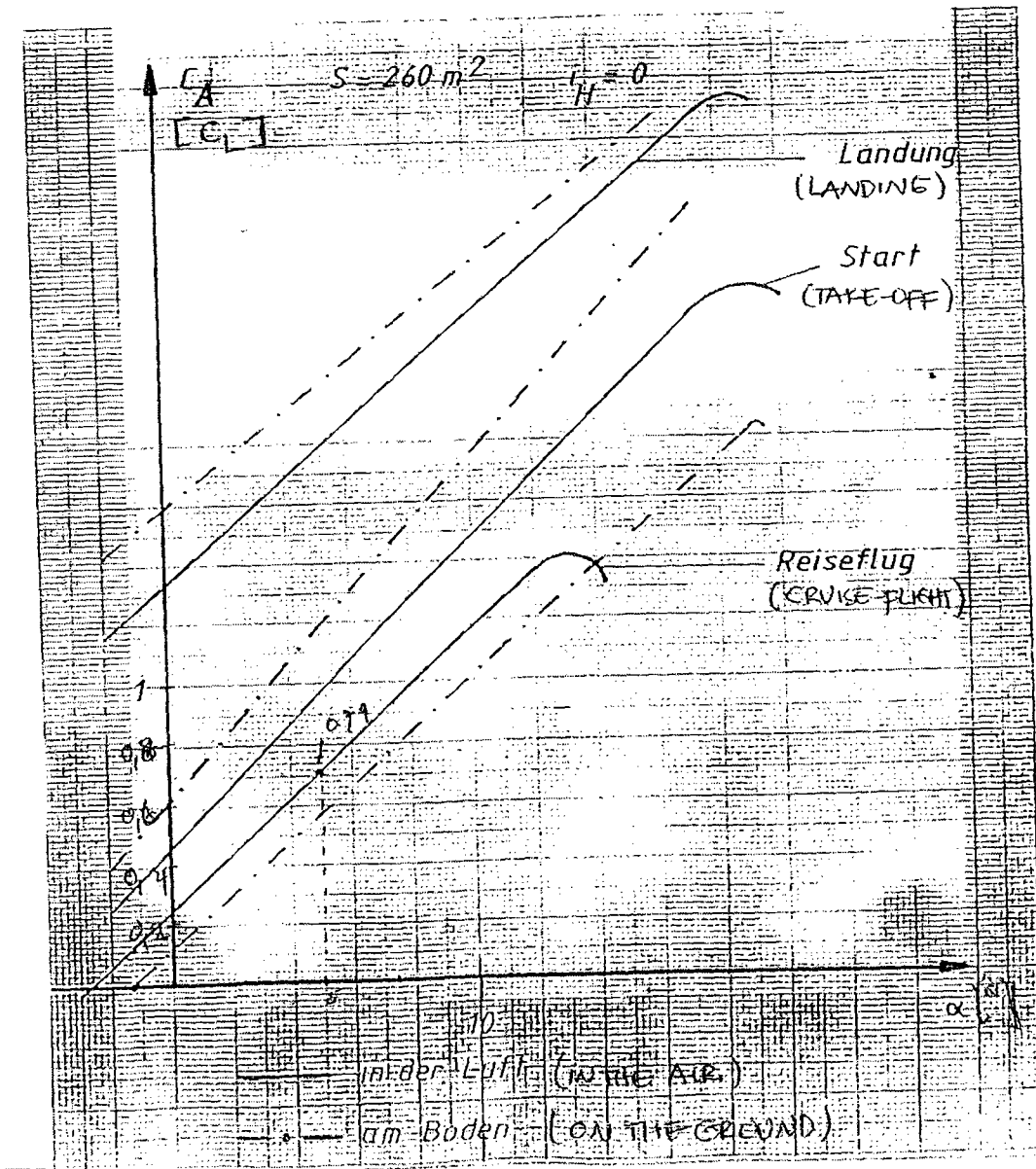


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Auftriebsanstieg als Funktion der Machzahl  
(LIFT-SLOPE AS FUNCTION OF MACH-NUMBER)



(LIFT-COEFFICIENT OF WHOLE AIRCRAFT  
AT SLOW AIRSPEEDS)  
Auftriebsbeiwert des Gesamtflugzeugs  
bei niedrigen Geschwindigkeiten

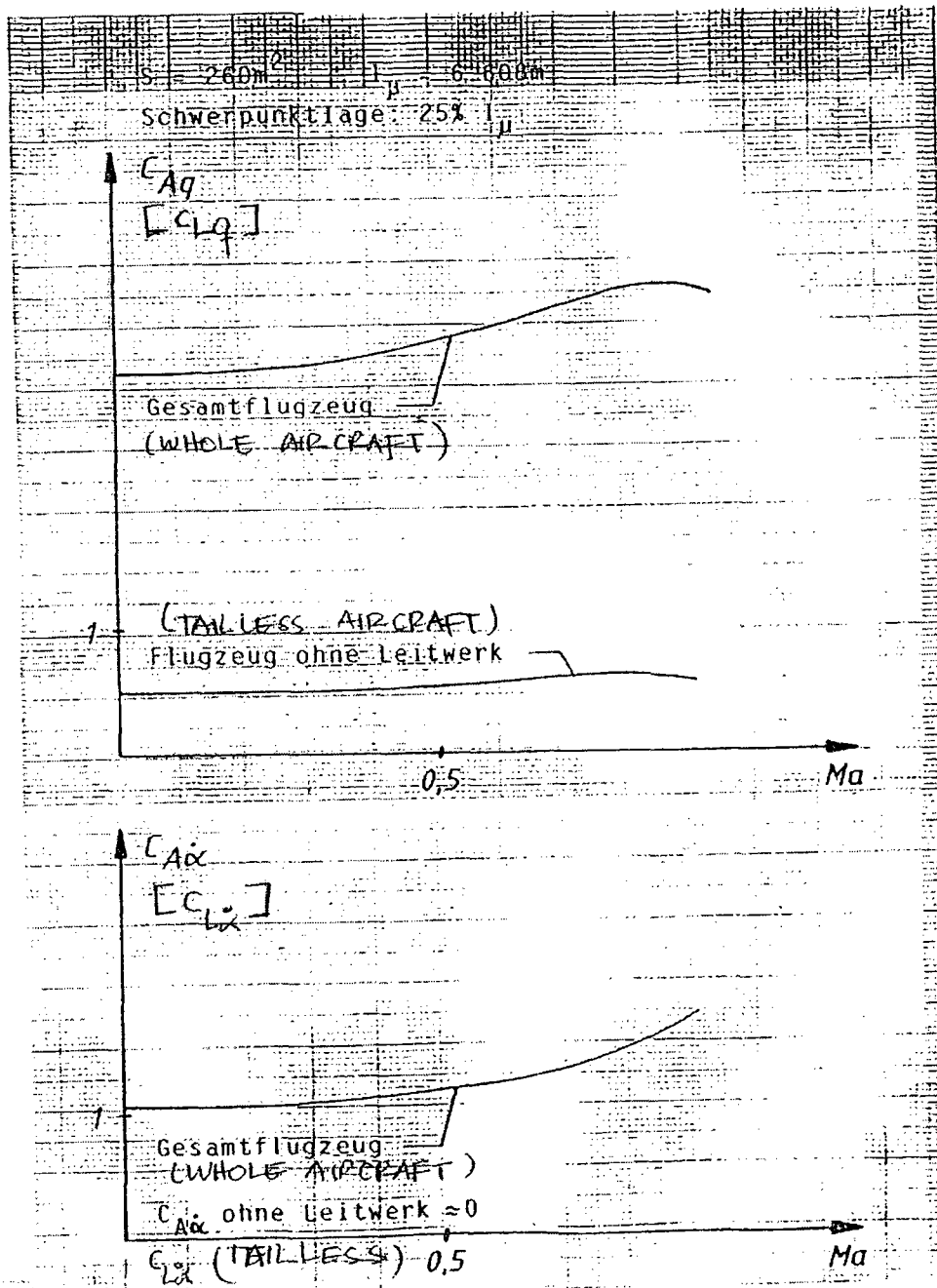


(LIFT-SLOPE DUE TO PITCH-RATE)

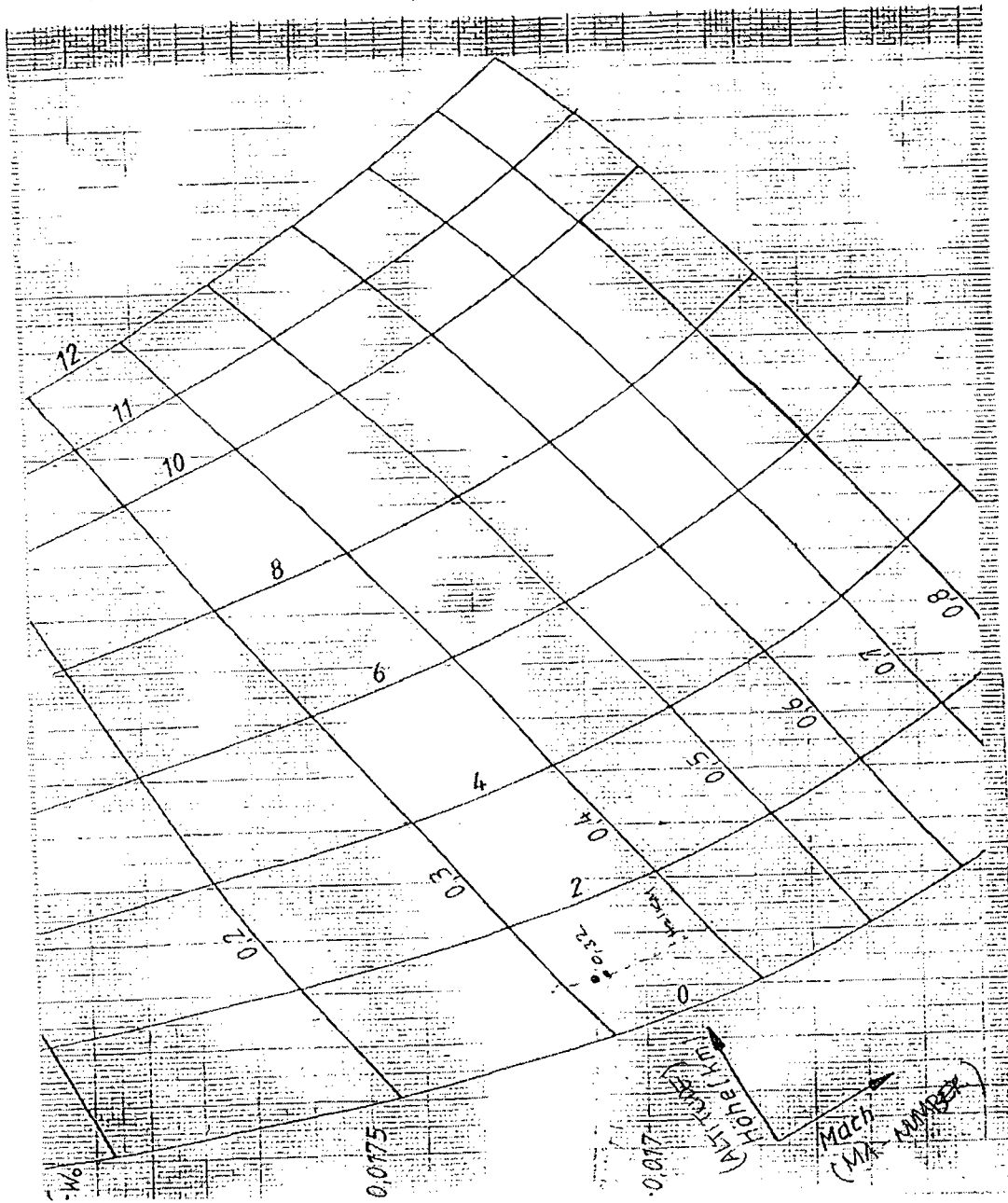
Auftriebsanstieg infolge Nickgeschwindigkeit

(LIFT-SLOPE DUE TO AOA-CHANGE)

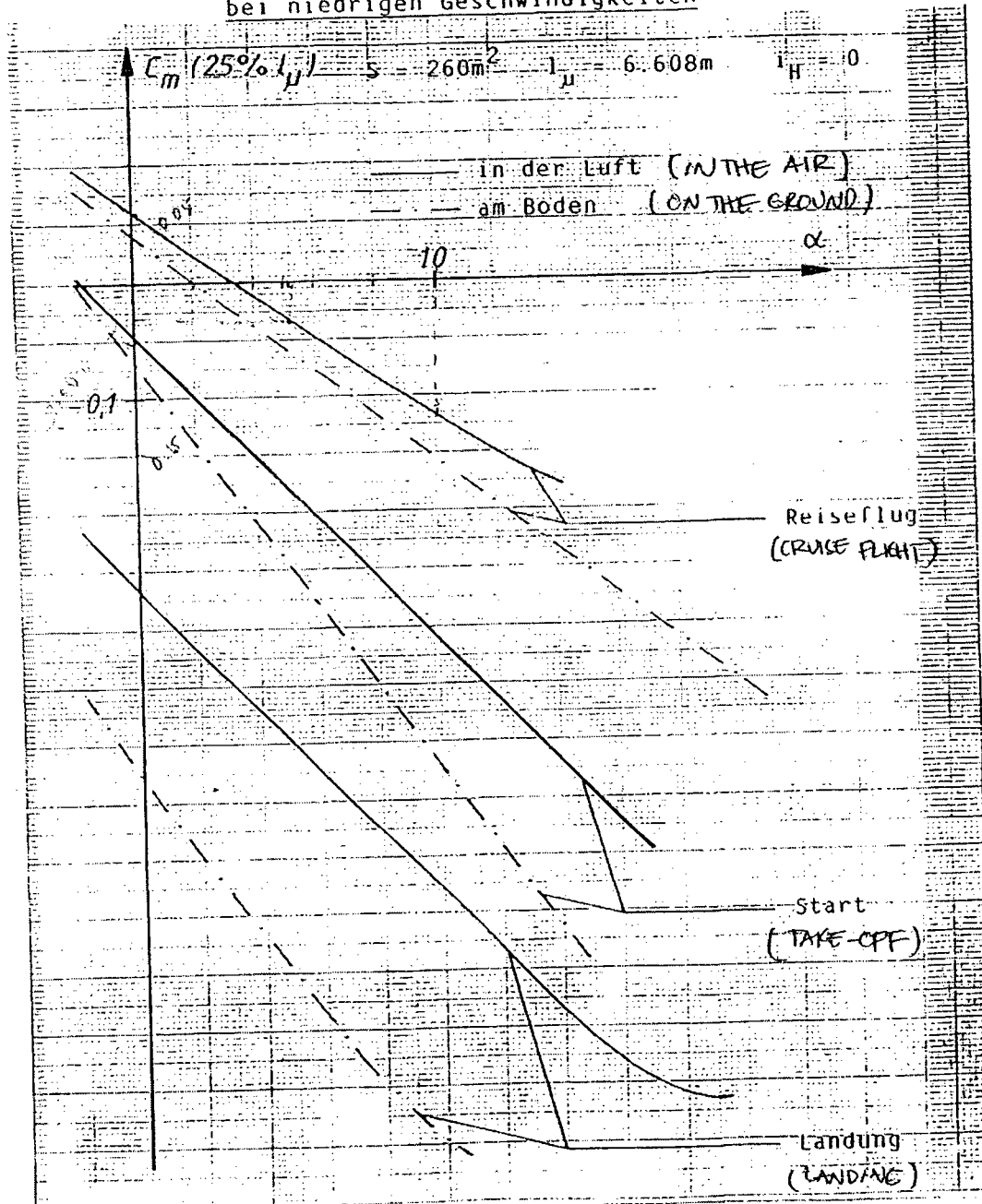
Auftriebsanstieg infolge Anstellwinkeländerung



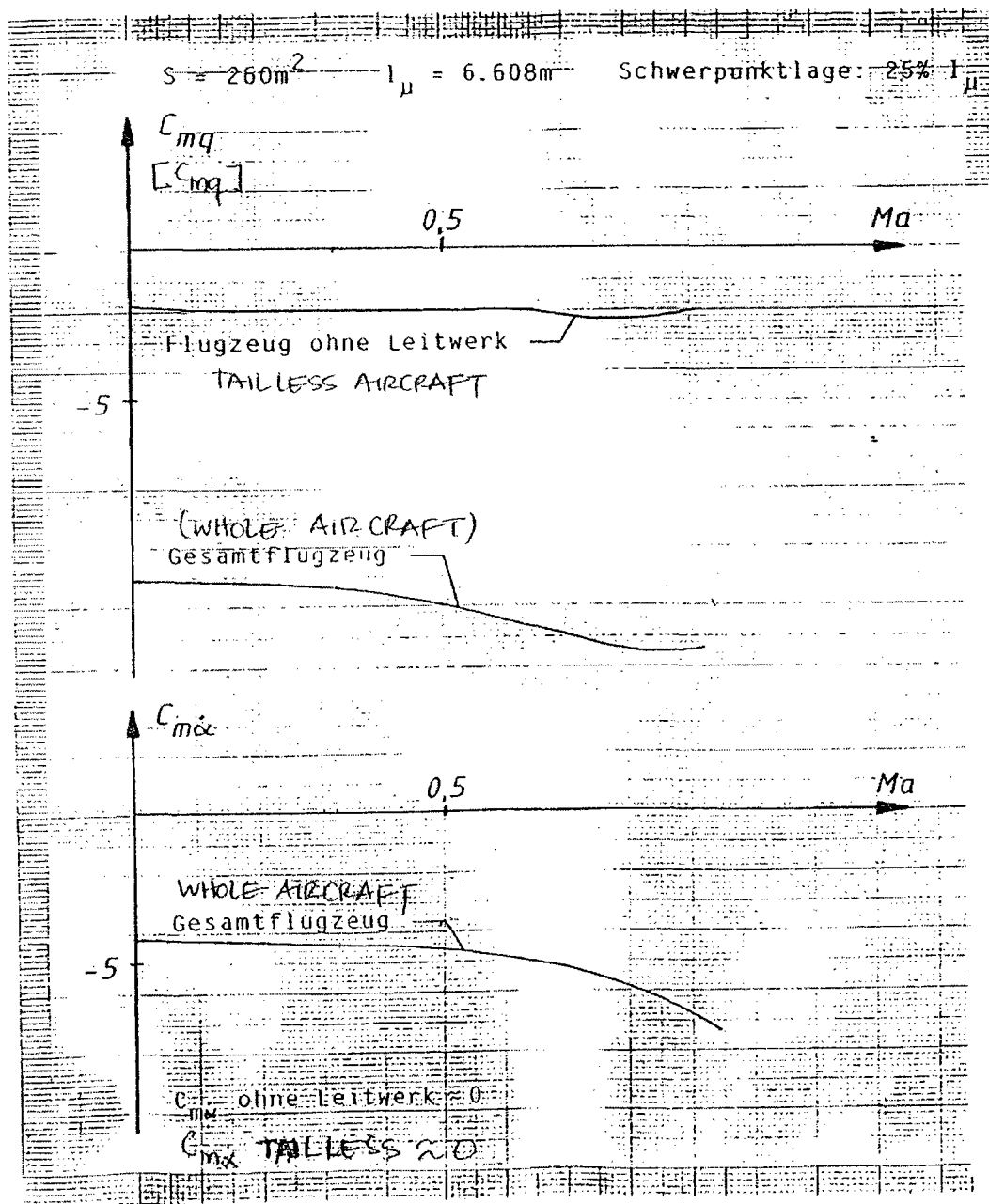
Nullwiderstandsbeiwert als Funktion von Höhe und Machzahl  
(ZERO DRAG COEFFICIENT ALS FUNCTION OF ALTITUDE & MA-NUMBER)



PITCH MOMENT COEFFICIENT OF WHOLE AIRCRAFT  
AT LOW AIRSPEEDS  
Nickmomentenbeiwert des Gesamtflugzeugs  
bei niedrigen Geschwindigkeiten

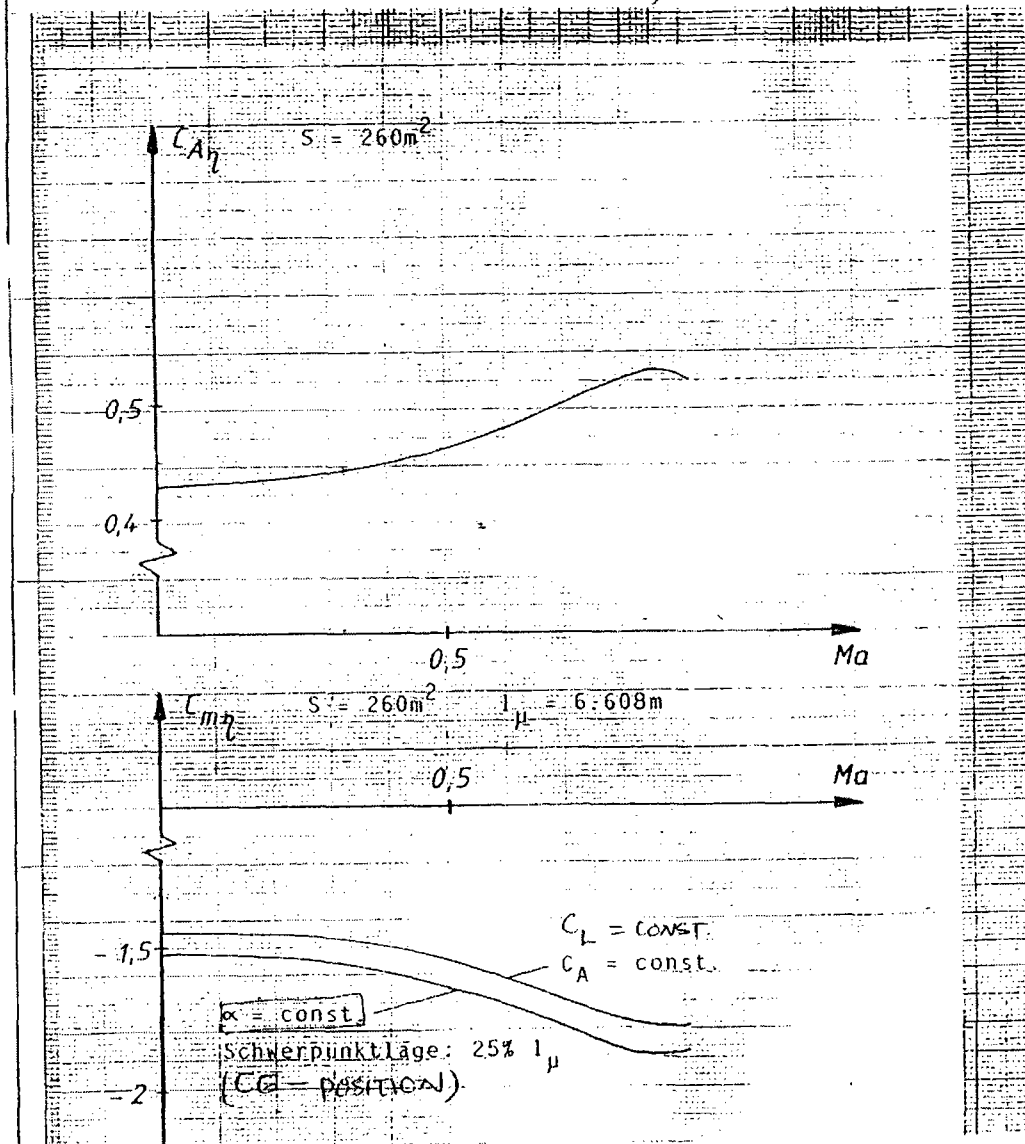


Nickdämpfung und Abwindverzögerung  
 PITCH DAMPING & UPWIND LAG

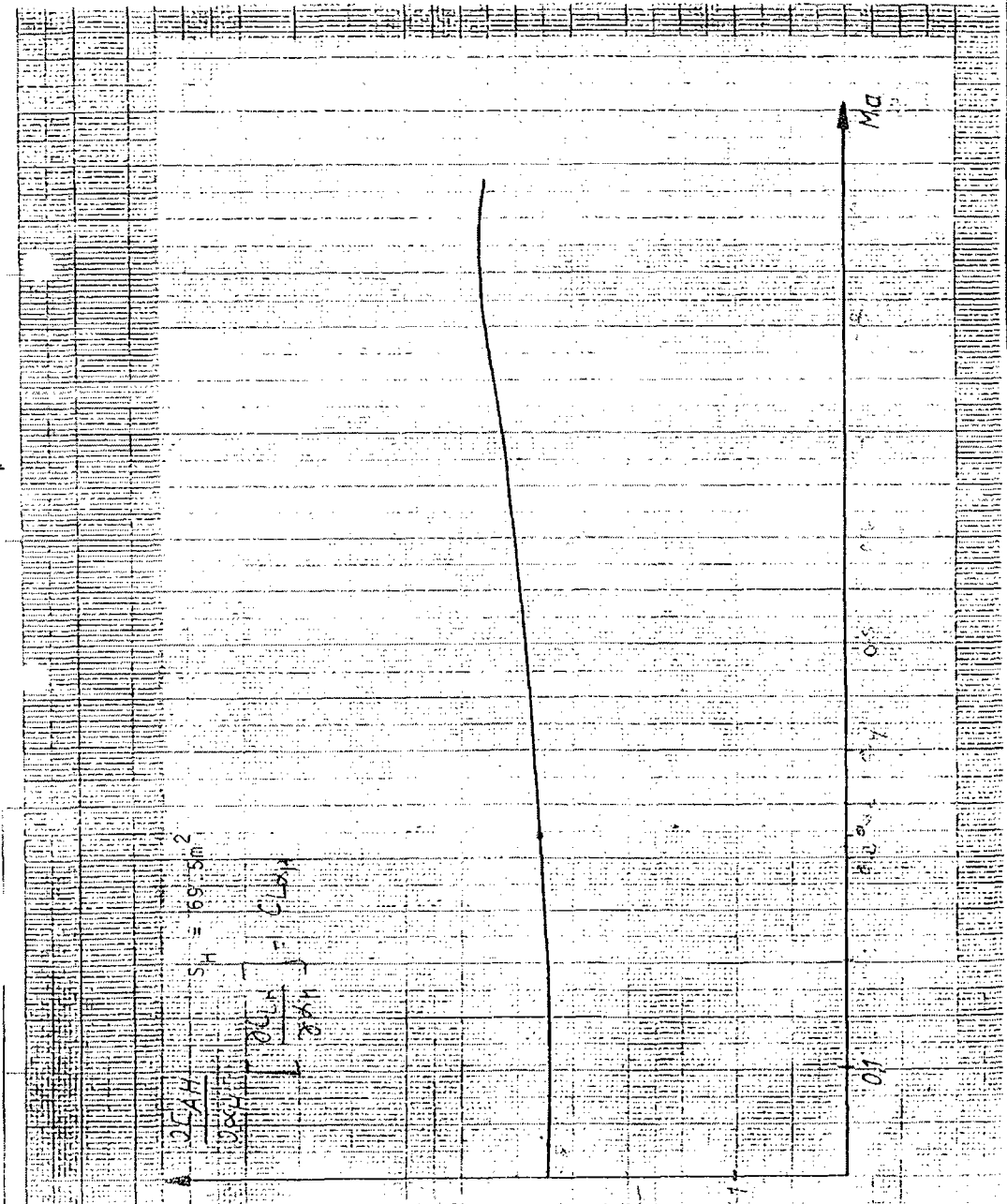




Höhenruderwirksamkeit  
(ELEVATOR-EFFECTIVENESS)



Auftriebsgradient des Höhenruders  
(LIFT COEFFICIENT OF ELEVATOR)



Abwindwinkel des Leitwerks  
(DOWNWASH ANGLE OF HORIZONTAL TAIL)

